



The information provided in this documentation contains general descriptions and/or technical characteristics of the performance of the products contained herein. This documentation is not intended as a substitute for and is not to be used for determining suitability or reliability of these products for specific user applications. It is the duty of any such user or integrator to perform the appropriate and complete risk analysis, evaluation and testing of the products with respect to the relevant specific application or use thereof. Neither Schneider Electric Industries SAS nor any of its affiliates or subsidiaries shall be responsible or liable for misuse of the information contained herein.



Main

Range of product	Altivar Process ATV600
Product or component type	Variable speed drive
Product specific application	Process and utilities
Device short name	ATV630
Variant	Standard version
Product destination	Asynchronous motors Synchronous motors
EMC filter	Integrated with 25 m conforming to EN/IEC 61800-3 category C3
IP degree of protection	IP00 conforming to IEC 61800-5-1 IP00 conforming to IEC 60529 IP20 (with kit VW3A9705) conforming to IEC 61800-5-1 IP20 (with kit VW3A9705) conforming to IEC 60529
Type of cooling	Forced convection
Supply frequency	50...60 Hz - 5...5 %
[Us] rated supply voltage	500...690 V - 15...10 %
Motor power kW	18.5 KW at 500 V (normal duty) 15 KW at 500 V (heavy duty) 22 KW at 690 V (normal duty) 18.5 KW at 690 V (heavy duty)
Motor power hp	25 Hp at 500 V normal duty 20 Hp at 500 V heavy duty 30 Hp at 690 V normal duty 25 hp at 690 V heavy duty
Line current	27.6 A at 500 V (normal duty) 26 A at 690 V (normal duty) 23.2 A at 500 V (heavy duty) 23 A at 690 V (heavy duty)
Prospective line Isc	70 kA
Apparent power	31.1 KVA at 690 V (normal duty) 27.5 kVA at 690 V (heavy duty)
Continuous output current	29 A at 4 kHz for normal duty 24 A at 4 kHz for heavy duty
Maximum transient current	31.9 A during 60 s (normal duty) 36 A during 60 s (heavy duty)
Asynchronous motor control profile	Constant torque standard Optimized torque mode Variable torque standard
Synchronous motor control profile	Permanent magnet motor Synchronous reluctance motor
Speed drive output frequency	0.1...599 Hz
Nominal switching frequency	4 kHz
Switching frequency	2...8 kHz adjustable 4...8 kHz with derating factor
Safety function	STO (safe torque off) SIL 3
Discrete input logic	16 preset speeds

Communication port protocol	Modbus TCP Ethernet Modbus serial
Option card	Slot A: communication module, Profibus DP V1 Slot A: communication module, Profinet Slot A: communication module, DeviceNet Slot A: communication module, Modbus TCP/ EtherNet/IP Slot A: communication module, CANopen daisy chain RJ45 Slot A: communication module, CANopen SUB-D 9 Slot A: communication module, CANopen screw terminals Slot A/slot B: digital and analog I/O extension module Slot A/slot B: output relay extension module Slot A: communication module, Ethernet IP/Modbus TCP/M-D-Link Communication module, BACnet MS/TP Communication module, Ethernet Powerlink

Complementary

Mounting mode	Wall mount
Output voltage	<= power supply voltage
Permissible temporary current boost	1.1 x In during 60 s (normal duty) 1.5 x In during 60 s (heavy duty)
Motor slip compensation	Not available in permanent magnet motor law Automatic whatever the load Can be suppressed Adjustable
Acceleration and deceleration ramps	S, U or customized Linear adjustable separately from 0.01...9999 s
Braking to standstill	By DC injection
Protection type	Thermal protection: motor Safe torque off: motor Motor phase break: motor Thermal protection: drive Safe torque off: drive Overheating: drive Overcurrent between output phases and earth: drive Overload of output voltage: drive Short-circuit protection: drive Motor phase break: drive Overvoltages on the DC bus: drive Line supply overvoltage: drive Line supply undervoltage: drive Line supply phase loss: drive Overspeed: drive Break on the control circuit: drive
Frequency resolution	Display unit: 0.1 Hz Analog input: 0.012/50 Hz
Electrical connection	Control: removable screw terminals 0.5...1.5 mm ² /AWG 20...AWG 16 Motor: screw terminal 10 mm ² /AWG 8 Line side: screw terminal 10 mm ² /AWG 8
Connector type	RJ45 (on the remote graphic terminal) for Ethernet/Modbus TCP RJ45 (on the remote graphic terminal) for Modbus serial
Exchange mode	Half duplex, full duplex, autonegotiation Ethernet/Modbus TCP
Number of addresses	1...247 for Modbus serial
Method of access	Slave Modbus TCP
Supply	External supply for digital inputs: 24 V DC (19...30 V), <1.25 mA, protection type: overload and short-circuit protection Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC +/- 5 %, <10 mA, protection type: overload and short-circuit protection Internal supply for digital inputs and STO: 24 V DC (21...27 V), <200 mA, protection type: overload and short-circuit protection
Local signalling	3 LEDs for local diagnostic 3 LEDs (dual colour) for embedded communication status 4 LEDs (dual colour) for communication module status 1 LED (red) for presence of voltage
Width	246 mm
Height	420 mm

Depth	242 mm
Net weight	22 kg
Analogue input number	3
Analogue input type	AI1, AI2, AI3 software-configurable voltage: 0...10 V DC, impedance: 30 kOhm, resolution 12 bits AI1, AI2, AI3 software-configurable current: 0...20 mA/4...20 mA, impedance: 250 Ohm, resolution 12 bits
Discrete input number	8
Discrete input type	DI1...DI6 programmable, 24 V DC (<= 30 V), impedance: 3.5 kOhm DI5, DI6 programmable as pulse input: 0...30 kHz, 24 V DC (<= 30 V) STOA, STOB safe torque off, 24 V DC (<= 30 V), impedance: > 2.2 kOhm
Input compatibility	DI1...DI6: discrete input level 1 PLC conforming to EN/IEC 61131-2 DI5, DI6: discrete input level 1 PLC conforming to IEC 65A-68 STOA, STOB: discrete input level 1 PLC conforming to EN/IEC 61131-2
Discrete input logic	Positive logic (source) (DI1...DI6), < 5 V (state 0), > 11 V (state 1) Negative logic (sink) (DI1...DI6), > 16 V (state 0), < 10 V (state 1) Positive logic (source) (DI5, DI6), < 0.6 V (state 0), > 2.5 V (state 1) Positive logic (source) (STOA, STOB), < 5 V (state 0), > 11 V (state 1)
Analogue output number	2
Analogue output type	Software-configurable voltage AO1, AO2: 0...10 V DC impedance 470 Ohm, resolution 10 bits Software-configurable current AO1, AO2: 0...20 mA, resolution 10 bits
Sampling duration	2 Ms +/- 0.5 ms (DI1...DI4) - discrete input 5 Ms +/- 1 ms (DI5, DI6) - discrete input 5 Ms +/- 0.1 ms (AI1, AI2, AI3) - analog input 10 ms +/- 1 ms (AO1) - analog output
Accuracy	+/- 0.6 % AI1, AI2, AI3 for a temperature variation 60 °C analog input +/- 1 % AO1, AO2 for a temperature variation 60 °C analog output
Linearity error	AI1, AI2, AI3: +/- 0.15 % of maximum value for analog input AO1, AO2: +/- 0.2 % for analog output
Relay output number	3
Relay output type	Configurable relay logic R1: fault relay NO/NC electrical durability 100000 cycles Configurable relay logic R2: sequence relay NO electrical durability 100000 cycles Configurable relay logic R3: sequence relay NO electrical durability 100000 cycles
Refresh time	Relay output (R1, R2, R3): 5 ms (+/- 0.5 ms)
Minimum switching current	Relay output R1, R2, R3: 5 mA at 24 V DC
Maximum switching current	Relay output R1, R2, R3 on resistive load, cos phi = 1: 3 A at 250 V AC Relay output R1, R2, R3 on resistive load, cos phi = 1: 3 A at 30 V DC Relay output R1, R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R1, R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC
Isolation	Between power and control terminals

Environment

Insulation resistance	> 1 MOhm 500 V DC for 1 minute to earth
Noise level	52 dB conforming to 86/188/EEC
Power dissipation in W	Natural convection: 138 W at 500 V, switching frequency 4 kHz Forced convection: 463 W at 500 V, switching frequency 4 kHz
Volume of cooling air	330 m3/h
Operating position	Vertical +/- 10 degree
Maximum THDI	<48 % with external line choke conforming to IEC 61000-3-12
Electromagnetic compatibility	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6
Pollution degree	2 conforming to EN/IEC 61800-5-1
Vibration resistance	1.5 mm peak to peak (f= 2...13 Hz) conforming to IEC 60068-2-6 1 gn (f= 13...200 Hz) conforming to IEC 60068-2-6
Shock resistance	15 gn for 11 ms conforming to IEC 60068-2-27
Relative humidity	5...95 % without condensation conforming to IEC 60068-2-3
Ambient air temperature for operation	-15...50 °C (without derating) 50...60 °C (with derating factor)

Ambient air temperature for storage	-40...70 °C
Operating altitude	<= 1000 m without derating 1000...4800 m with current derating 1 % per 100 m
Standards	UL 508C EN/IEC 61800-3 Environment 2 category C3 EN/IEC 61800-3 EN/IEC 61800-5-1 IEC 61000-3-12 IEC 60721-3 IEC 61508 IEC 13849-1
Product certifications	UL CSA TÜV
Marking	CE

Packing Units

Package 1 Weight	21.000 kg
Package 1 Height	48.500 cm
Package 1 width	39.500 cm
Package 1 Length	80.000 cm

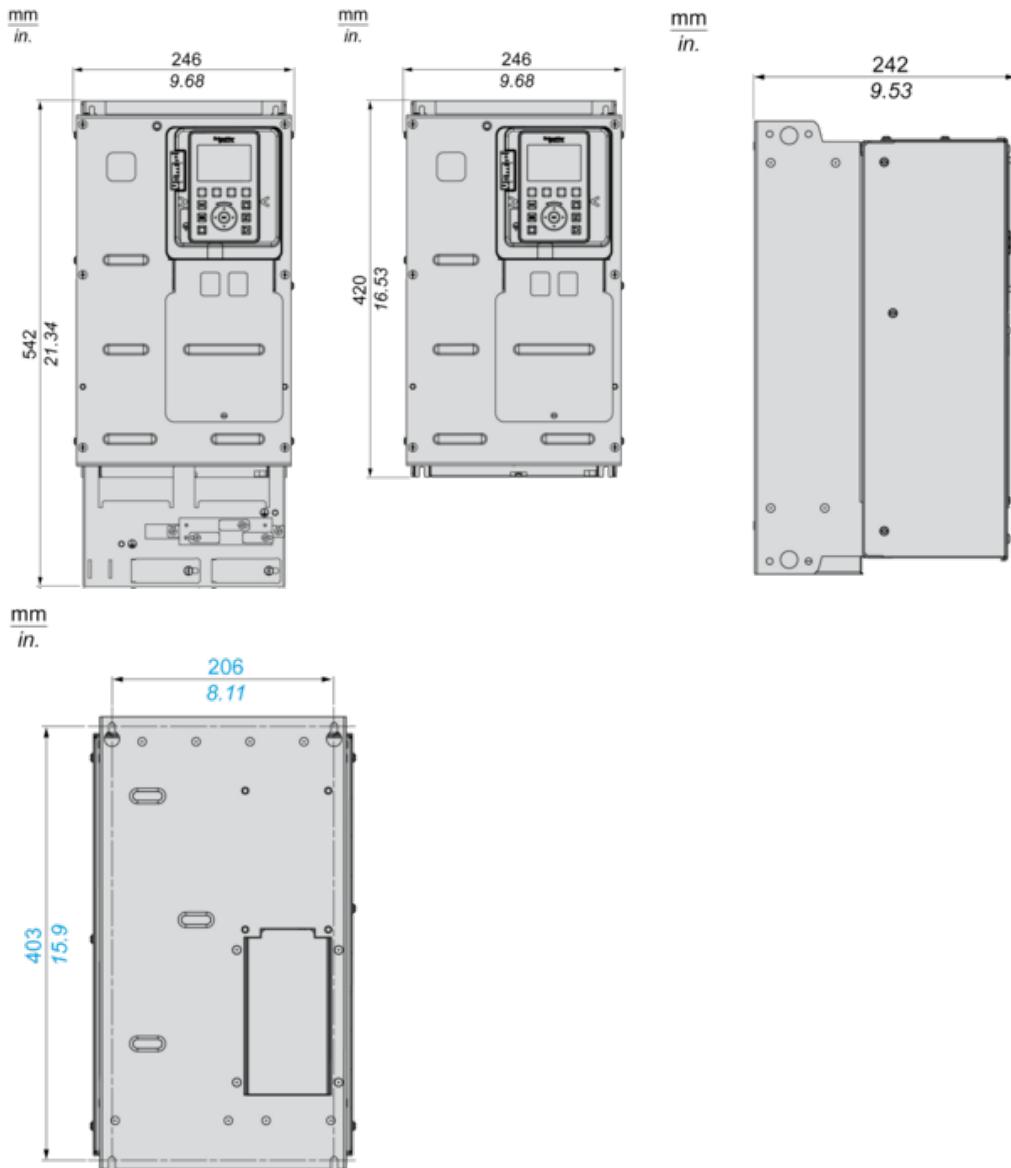
Offer Sustainability

Sustainable offer status	Green Premium product
REACH Regulation	<input checked="" type="checkbox"/> REACH Declaration
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope) <input checked="" type="checkbox"/> EU RoHS Declaration
Mercury free	Yes
RoHS exemption information	<input checked="" type="checkbox"/> Yes
China RoHS Regulation	<input checked="" type="checkbox"/> China RoHS Declaration
Environmental Disclosure	<input checked="" type="checkbox"/> Product Environmental Profile
Circularity Profile	<input checked="" type="checkbox"/> End Of Life Information
WEEE	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins
Upgradeability	<input checked="" type="checkbox"/> Upgraded Components Available

Dimensions

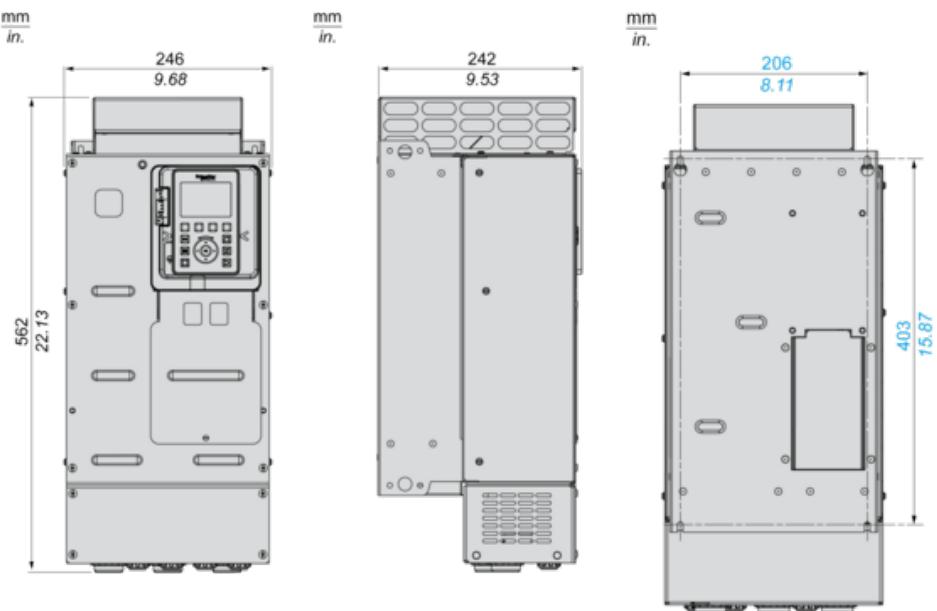
Drives without Top Cover

Front View with EMC Plate, Front, Left and Rear Views without EMC Plate

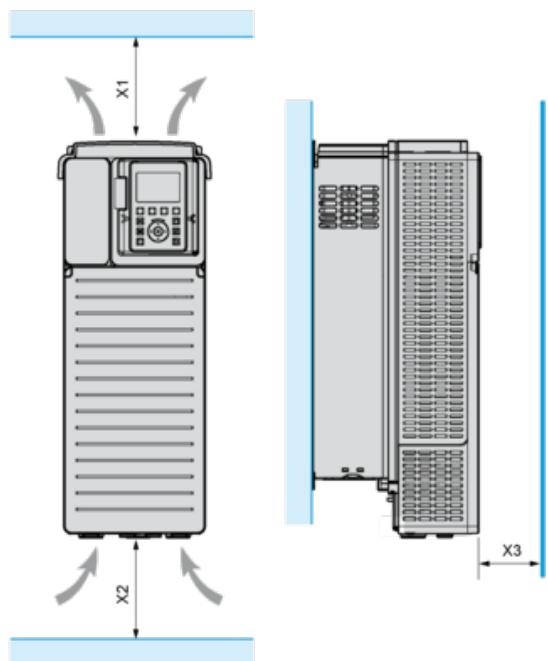


Drives with IP20 Top Cover

Front, Left and Rear Views



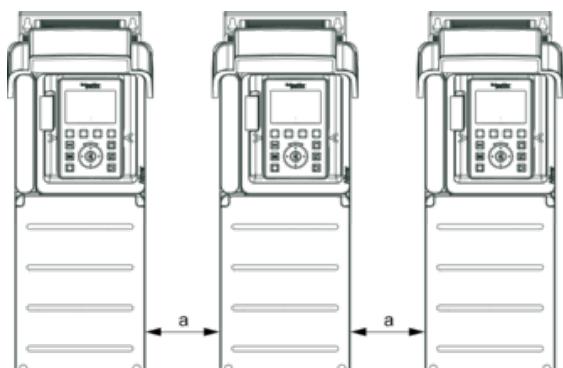
Clearances



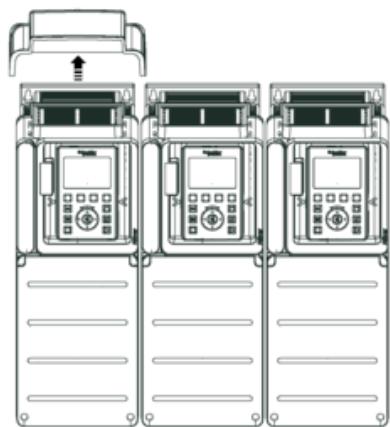
X1	X2	X3
$\geq 100 \text{ mm (3.94 in.)}$	$\geq 100 \text{ mm (3.94 in.)}$	$\geq 10 \text{ mm (0.39 in.)}$

Mounting Types

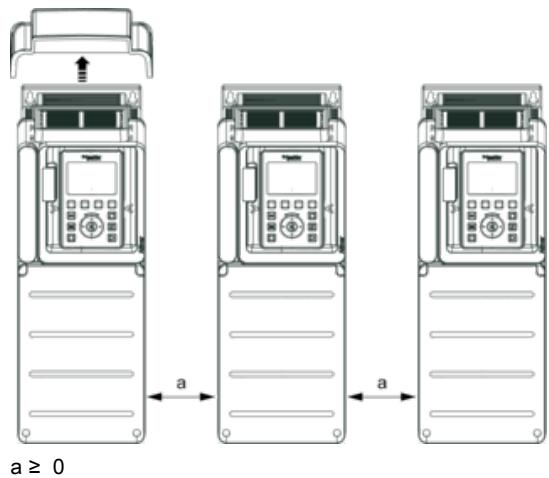
Mounting Type A: Individual IP21



Mounting Type B: Side by Side IP20

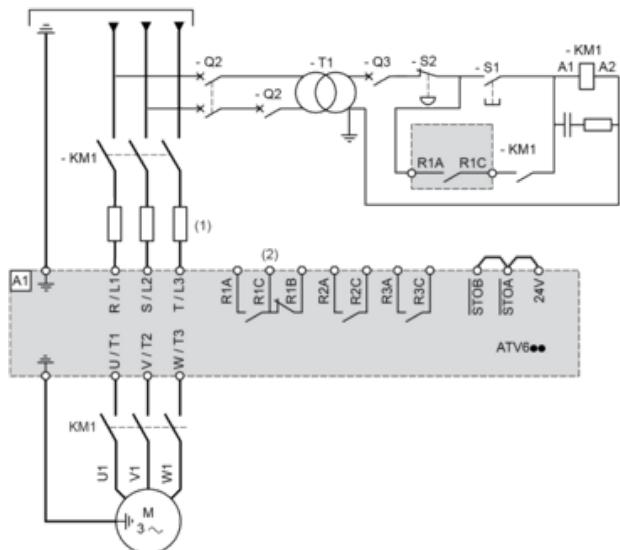


Mounting Type C: Individual IP20



Three-Phase Power Supply with Upstream Breaking via Line Contactor

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



(1) Line choke if used

(2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.

A1 : Drive

KM1 : Line Contactor

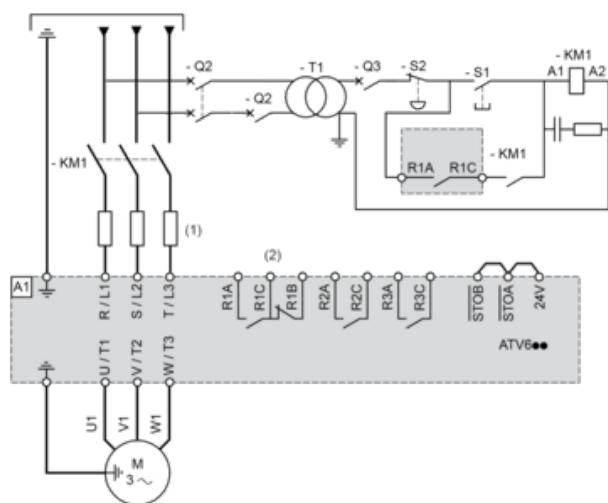
Q2, Q3 : Circuit breakers

S1, S2 : Pushbuttons

T1 : Transformer for control part

Three-Phase Power Supply with Downstream Breaking via Contactor

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



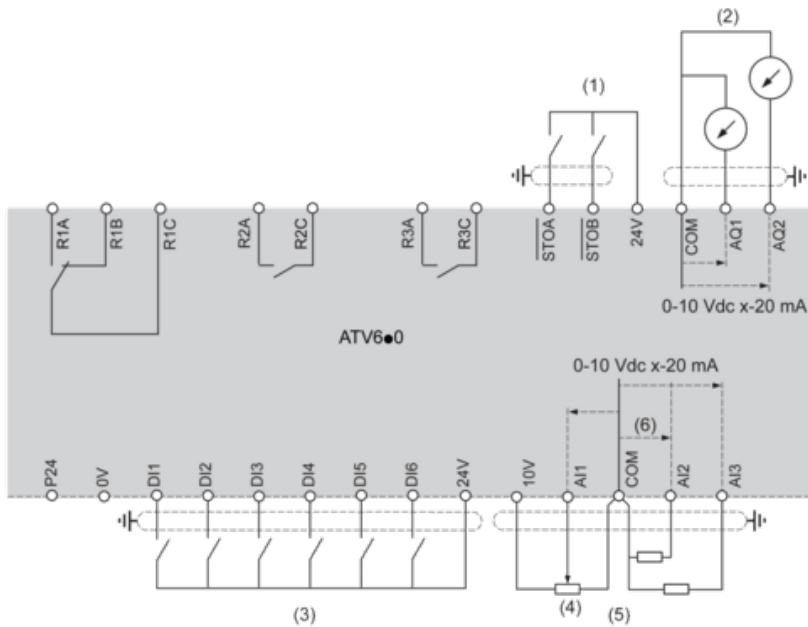
(1) Line choke if used

(2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.

A1 : Drive

KM1 : Contactor

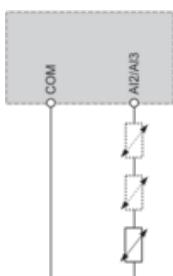
Control Block Wiring Diagram



- (1) Safe Torque Off
- (2) Analog Output
- (3) Digital Input
- (4) Reference potentiometer
- (5) Analog Input
- R1A, R1B, R1C : Fault relay
- R2A, R2C : Sequence relay
- R3A, R3C : Sequence relay

Sensor Connection

It is possible to connect either 1 or 3 sensors on terminals AI2 or AI3.

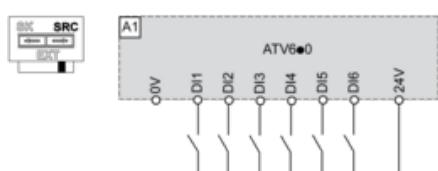


Sink / Source Switch Configuration

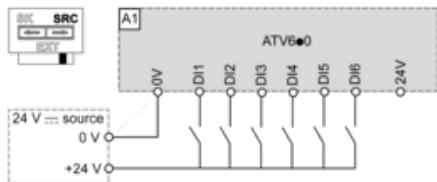
The switch is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

- Set the switch to Source (factory setting) if using PLC outputs with PNP transistors.
- Set the switch to Ext if using PLC outputs with NPN transistors.

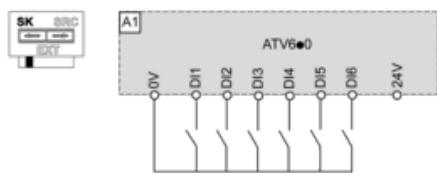
Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs



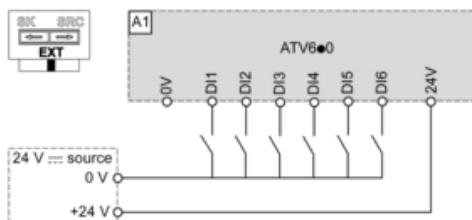
Switch Set to SRC (Source) Position and Use of an External Power Supply for the DI



Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs



Switch Set to EXT Position Using an External Power Supply for the DI



Derating Curves

