BSH1403T21F2P

servo motor BSH, Lexium 32, 27.8N.m, 3000rpm, 140mm, untapped shaft, Sincos single turn, with brake, IP65





Main

Product or component type	Servo motor
Device short name	BSH
Maximum mechanical speed	4800 rpm
Continuous stall torque	27.8 N.M for LXM32.D72N4 at 24 A, 400 V, three phase 27.8 N.m for LXM32.D72N4 at 24 A, 480 V, three phase
Peak stall torque	90.2 N.M for LXM32.D72N4 at 24 A, 400 V, three phase 90.2 N.m for LXM32.D72N4 at 24 A, 480 V, three phase
Nominal output power	4100 W for LXM32.D72N4 at 24 A, 400 V, three phase 4100 W for LXM32.D72N4 at 24 A, 480 V, three phase
Nominal torque	12.9 N.M for LXM32.D72N4 at 24 A, 400 V, three phase 12.9 N.m for LXM32.D72N4 at 24 A, 480 V, three phase
Nominal speed	3000 rpm for LXM32.D72N4 at 24 A, 400 V, three phase 3000 rpm for LXM32.D72N4 at 24 A, 480 V, three phase
Product compatibility	LXM32.D72N4 at 400 V three phase LXM32.D72N4 at 480 V three phase
Shaft end	Untapped
IP degree of protection	IP65 standard IP67 with IP67 kit
Speed feedback resolution	131072 points/turn
Holding brake	With
Mounting support	International standard
Electrical connection	Rotatable right-angled connectors

Complementary

Range compatibility	Lexium 32			
Supply voltage max	480 V			
Network number of phases	Three phase			
Continuous stall current	22.3 A			
Maximum continuous power	3.3 W			
Maximum current Irms	72 A for LXM32.D72N4			
Maximum permanent current	81.3 A			
Switching frequency	8 kHz			
Second shaft	Without second shaft end			
Shaft diameter	24 mm			
Shaft length	50 mm			
Feedback type	Single turn SinCos Hiperface			
Holding torque	36 N.m holding brake			

Number of motor stacks Torque constant 1.58 N.m/A at 120 °C Back emf constant 105 V/krpm at 120 °C Number of motor poles 10 Rotor inertia 14.48 kg.cm² Stator resistance 0.4 Ohm at 20 °C Stator inductance 5.1 mH at 20 °C Stator electrical time constant 12.75 ms at 20 °C Maximum radial force Fr 1780 N at 3000 rpm 2030 N at 2000 rpm 2560 N at 1000 rpm Maximum axial force Fa 0.2 x Fr Brake pull-in power 26 W Type of cooling Natural convection					
Back emf constant 105 V/krpm at 120 °C Number of motor poles 10 Rotor inertia 14.48 kg.cm² Stator resistance 0.4 Ohm at 20 °C Stator inductance 5.1 mH at 20 °C Stator electrical time constant 12.75 ms at 20 °C Maximum radial force Fr 1780 N at 3000 rpm 2030 N at 2000 rpm 2560 N at 1000 rpm Maximum axial force Fa 0.2 x Fr Brake pull-in power 26 W					
Number of motor poles 10 Rotor inertia 14.48 kg.cm² Stator resistance 0.4 Ohm at 20 °C Stator inductance 5.1 mH at 20 °C Stator electrical time constant 12.75 ms at 20 °C Maximum radial force Fr 1780 N at 3000 rpm 2030 N at 2000 rpm 2560 N at 1000 rpm Maximum axial force Fa 0.2 x Fr Brake pull-in power 26 W	1.58 N.m/A at 120 °C				
Rotor inertia 14.48 kg.cm² Stator resistance 0.4 Ohm at 20 °C Stator inductance 5.1 mH at 20 °C Stator electrical time constant 12.75 ms at 20 °C Maximum radial force Fr 1780 N at 3000 rpm 2030 N at 2000 rpm 2560 N at 1000 rpm Maximum axial force Fa 0.2 x Fr Brake pull-in power 26 W					
Stator resistance 0.4 Ohm at 20 °C Stator inductance 5.1 mH at 20 °C Stator electrical time constant 12.75 ms at 20 °C Maximum radial force Fr 1780 N at 3000 rpm 2030 N at 2000 rpm 2560 N at 1000 rpm Maximum axial force Fa 0.2 x Fr Brake pull-in power 26 W					
Stator inductance 5.1 mH at 20 °C Stator electrical time constant 12.75 ms at 20 °C Maximum radial force Fr 1780 N at 3000 rpm 2030 N at 2000 rpm 2560 N at 1000 rpm Maximum axial force Fa 0.2 x Fr Brake pull-in power 26 W					
Stator electrical time constant 12.75 ms at 20 °C Maximum radial force Fr 1780 N at 3000 rpm 2030 N at 2000 rpm 2560 N at 1000 rpm Maximum axial force Fa 0.2 x Fr Brake pull-in power 26 W	0.4 Ohm at 20 °C				
Maximum radial force Fr 1780 N at 3000 rpm 2030 N at 2000 rpm 2560 N at 1000 rpm Maximum axial force Fa 0.2 x Fr Brake pull-in power 26 W					
2030 N at 2000 rpm 2560 N at 1000 rpm Maximum axial force Fa 0.2 x Fr Brake pull-in power 26 W					
Brake pull-in power 26 W	2030 N at 2000 rpm				
7 - P - P - P - P - P - P - P - P - P -	0.2 x Fr				
Type of cooling Natural convection					
Length 365.5 mm					
Centring collar diameter 130 mm	130 mm				
Centring collar depth 3.5 mm	3.5 mm				
Number of mounting holes 4					
Mounting holes diameter 11 mm	11 mm				
Circle diameter of the mounting holes 165 mm					
Net weight 23 kg	23 kg				

Packing Units

PCE
1
27.0 cm
27.0 cm
48.2 cm
13.29 kg
-

Offer Sustainability

Sustainable offer status	Green Premium product			
REACh Regulation	☑ REACh Declaration			
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope)			
Mercury free	Yes			
China RoHS Regulation	☑ China RoHS Declaration			
RoHS exemption information	₫Yes			
Environmental Disclosure	Product Environmental Profile			
Circularity Profile	No need of specific recycling operations			
WEEE	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins			
PVC free	Yes			

Contractual warranty

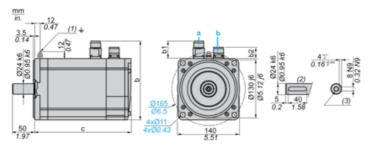
Warranty 18 months

Product data sheet Dimensions Drawings

BSH1403T21F2P

Servo Motors Dimensions

Example with Straight Connectors



- a: Power supply for servo motor brake
- b: Power supply for servo motor encoder
- (1) M4 screw
- (2) Shaft end, keyed slot (optional)
- (3) For screws M8 x 19 mm/M8 x 0.75 in.

Dimensions in mm

Straight connectors Rotatable angled connectors		c (without brake)	c (with brake)				
b	b1	b2	b	b1	b2		
192.5	54	25.5	198.5	60	39.5	328	366

Dimensions in in.

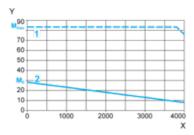
Straight cor	raight connectors Rotatable angled connectors		c (without brake)	c (with brake)			
b	b1	b2	b	b1	b2		
7.57	2.12	1.00	7.81	2.36	1.55	12.91	14.40

BSH1403T21F2P

400 V 3-Phase Supply Voltage

Torque/Speed Curves

Servo motor with LXM32•D72N4 servo drive



X Speed in rpm

Y Torque in Nm

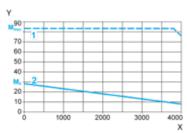
1 Peak torque

2 Continuous torque

480 V 3-Phase Supply Voltage

Torque/Speed Curves

Servo motor with LXM32•D72N4 servo drive



X Speed in rpm

Y Torque in Nm

1 Peak torque

2 Continuous torque